

Optimising the real world, robustly

An introduction to robust optimisation

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Agenda

- ▶ What is robust optimisation?
 - ▶ Why does it matter?
- ▶ A real world example
- ▶ Some simple examples
 - ▶ Shortest path
 - ▶ Knapsack

Pre-requisites

- ▶ Linear and mixed integer programming
- ▶ Modelling and implementation
- ▶ Desirable
 - ▶ Mosel modelling language
 - ▶ Installation of Xpress 7.7 or later

What is robust optimisation?

Why does it matter?

Why does robust optimisation matter?

- ▶ Optimisation problems often use data that are subject to **uncertainty**
 - ▶ inaccurate, erroneous, missing measurements
 - ▶ data that are not yet known
 - ▶ rely on estimates or extrapolations of historic data
 - ▶ influenced by external events not captured by the model
- ▶ How can we make decisions without knowing the parameters?

Why does robust optimisation matter?

- ▶ Key idea: although some parameters are uncertain, we might know how they vary
 - ▶ the accuracy of a given parameter is $\pm\varepsilon = 10^{-4}$
 - ▶ a vector of parameters \mathbf{u} has a mean $\hat{\mathbf{u}}$ and covariance matrix $\hat{\mathbf{Q}}$
- ▶ Some parameters are **uncertain** but we have good knowledge of the uncertainty set
- ▶ Robust optimisation finds a solution that is feasible **for any/all** values of the parameters in the uncertainty set

Why does robust optimisation matter?

- ▶ Robust optimisation is about finding the optimal solution of the worst case realisation of a problem
 - ▶ Accounting for data quality and forecast distribution during the optimisation process
- ▶ Describing the worst case scenario is not trivial
 - ▶ Infinite number of realisations
 - ▶ Unknown realisation space

Why does robust optimisation matter?

- ▶ Possible approaches
 - ▶ build into the model formulation
 - ▶ use suitable solution methods
 - ▶ post process results
- ▶ Robust optimisation provides a modelling paradigm that offers solutions when **uncertainty in the input data** can be bounded within a well described region
 - ▶ finds a solution that is feasible regardless of the realisation of the uncertain values
 - ▶ different from Stochastic Optimisation where the expected value is optimised

Robust optimisation in a nutshell (mathematical concepts)

▶ Deterministic problem

$$\text{▶ } \min_{x \in \mathbb{R}^n} \{c \cdot x \mid A \cdot x \geq b, D \cdot x \geq l\}$$

- ▶ A is the structural data of the problem. It is known for sure.
- ▶ D is an approximation of the real world.

▶ Robust counterpart

$$\text{▶ } \min_{x \in \mathbb{R}^n} \{c \cdot x \mid A \cdot x \geq b, (D + \xi a) \cdot x \geq l, \forall \xi \in U\}$$

$$\text{▶ } \min_{x \in \mathbb{R}^n} \left\{ c \cdot x \mid A \cdot x \geq b, \min_{\xi \in U} \{(D + \xi a) \cdot x\} \geq l \right\}$$

- ▶ U is the set of perturbations of non-structural data
- ▶ ξa is the error term
- ▶ x must be feasible for all possible perturbation
- ▶ U must be carefully designed to be tractable

Robust optimisation in a nutshell (constraints)

► Deterministic constraint

$$a_1x_1 + \dots + a_{k-1}x_{k-1} + a_kx_k + \dots + a_nx_n \leq b$$

where

a_i – coefficient

x_i – decision variable

Robust optimisation in a nutshell (constraints)

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a_i – coefficient

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► Robust constraint

$$a_1x_1 + \dots + a_{k-1}x_{k-1} + (a_k + u_k)x_k + \dots + (a_n + u_n)x_n \leq b$$

where

u_i – uncertainty on coefficient values

Robust optimisation in a nutshell (constraints)

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where

u_i – uncertainty on coefficient values

► Requirement: the uncertainty must be bounded

Robust optimisation in a nutshell (terminology)

- ▶ The feasible region of the **uncertains** is called the **uncertainty set**, it is modelled by means of constraints on the uncertain
- ▶ the type of a robust constraint is defined by the type of uncertainty set (or sets) on its uncertain
- ▶ solvability depends on whether the robust constraints can be transformed into a form (the so-called **robust counterpart**) that can be solved by the available mathematical solvers

Robust optimisation in a nutshell (robust counterparts)

► The Box

- Lower and upper bounds on possible value range

- $U = \{ \xi : \text{abs}(\xi_i) \leq d, \xi_i \in [\underline{\xi}_i, \overline{\xi}_i], \forall i \in N \}$

- Worst error term in a greater-than-equal constraint

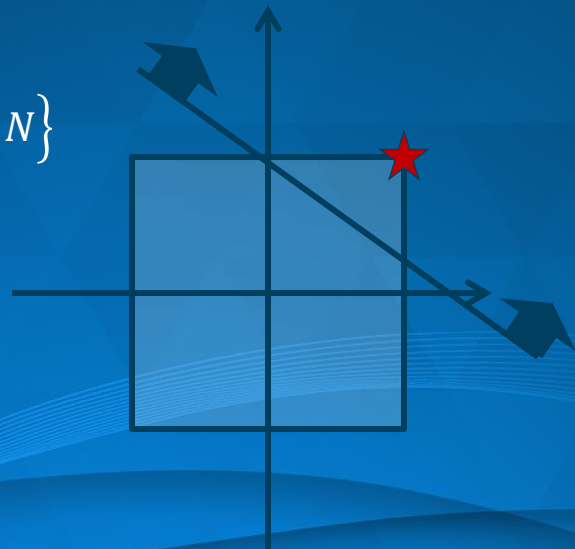
- $rc(x) = \min_{\xi \in U} \{ (\xi a) \cdot x : \text{abs}(\xi_i) \leq d, \xi_i \in [\underline{\xi}_i, \overline{\xi}_i], \forall i \in N \}$

- $x \geq 0, d \geq 0$

- Closed form solution

- $rc(x) = (\tilde{\xi} a) \cdot x$

- With $\tilde{\xi}_i = \min \left(\max(\underline{\xi}_i, -d), \min(\overline{\xi}_i, d) \right)$



Trivial

Robust optimisation in a nutshell (robust counterparts)

▶ The Ellipsoid

▶ Maximum distance or deviation

$$\text{▶ } U = \{\xi : \sum_i \xi_i^2 \leq d^2, \forall i \in N\}$$

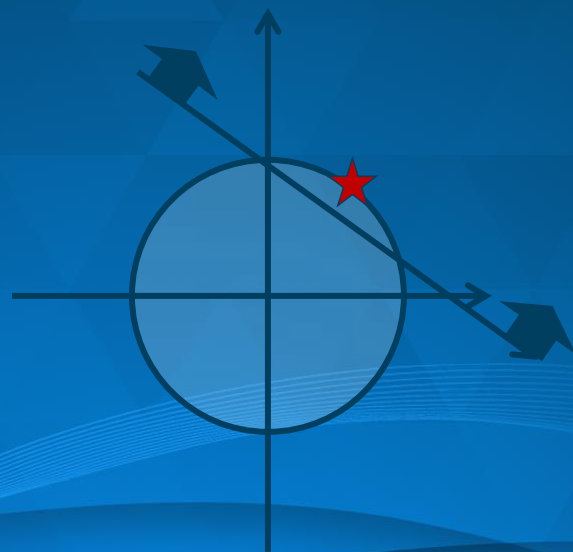
▶ Worst error term in a greater-than-equal constraint

$$\text{▶ } rc(x) = \min_{\xi \in U} \{(\xi a) \cdot x : \sum_i \xi_i^2 \leq d^2\}$$

$$\text{▶ } x \geq 0$$

▶ Closed form solution

$$\text{▶ } rc(x) = -d\sqrt{\sum_i (a_i \cdot x_i)^2}$$



Trivial

Robust optimisation in a nutshell (robust counterparts)

▶ The Polyhedron

▶ Linear dependency and bounds of error term

$$\text{▶ } U = \{\xi : \sum_i \xi_i \leq d, \forall i \in N\}$$

▶ Worst error term in a greater-than-equal constraint

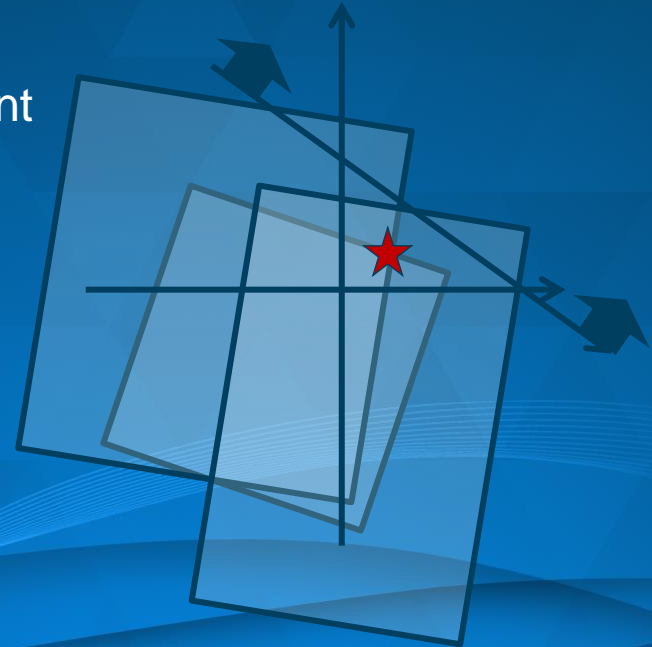
$$\text{▶ } rc(x) = \min_{\xi \in U} \{\xi \cdot x : \sum_i \xi_i \leq d\}$$

$$\text{▶ } x \geq 0$$

▶ Robust counterpart

▶ Assume $x \geq 0$, and fixed

▶ Apply LP Strong duality



Non-trivial

A real-world case: air products and chemicals¹

- ▶ Production planning at a liquid oxygen/nitrogen plant, a very energy-intensive operation
 - ▶ Interruptible Load Contract (ILC): power company can suspend supply in periods of high demand (summer)
 - ▶ At most k interruptions each month (8 hours each)
 - ▶ **Cheaper** (per kWh) than with uninterrupted contract
- ▶ The power supplier won't tell us when the interruptions will be
 - ▶ Treat the interruptions as uncertain
 - ▶ Plan production so that even with the most evil-placed k interruptions we satisfy customer demand

¹Latifoglu, C., Belotti, P., Snyder, L.V. (2013). Models for production planning under power interruptions. *Naval Research Logistics* **60**(5):413-431.

Original model

```
declarations
```

```
    produce: array (PERIODS, GASES) of mpvar  
    inventory: array (PERIODS, GASES) of mpvar
```

```
end-declarations
```

```
forall(t in PERIODS, g in GASES) do
```

```
    inventory(0, g) + sum(tp in PERIODS | tp <= t)  
        produce(tp, g) - DEMAND(tp, g)) >= 0  
    inventory(t, g) <= INV_CAP (g)  
    produce(t, g) <= PROD_CAP (g)
```

```
end-do
```

```
minimize(sum (t in PERIODS, g in GASES)  
    (PROD_COST * produce(t,g) + INV_COST * inventory(t,g)))
```

Robust model

```
declarations
```

```
    produce: array (PERIODS, GASES) of mpvar  
    inventory: array (PERIODS, GASES) of mpvar
```

```
    interrupt: array (PERIODS) of uncertain
```

```
end-declarations
```

```
forall(t in PERIODS, g in GASES) do
```

```
    inventory(0, g) + sum(tp in PERIODS | tp <= t)  
        ((1 - interrupt(tp)) * produce(tp, g) - DEMAND(tp, g)) >= 0
```

```
    inventory(t, g) <= INV_CAP (g)
```

```
    produce(t, g) <= PROD_CAP (g)
```

```
end-do
```

```
sum(t in PERIODS) interrupt (t) <= MAX_NINTERR
```

```
minimize(sum (t in PERIODS, g in GASES)
```

```
    (PROD_COST * produce(t,g) + INV_COST * inventory(t,g)))
```

The user vs. opponent

User vs. opponent perspective

- ▶ Robustness implies we are prepared against **any** realisation of u .
 - ▶ We (the user) have power over the decision variables x
 - ▶ Uncertain parameters u are **not** in our control
 - ▶ An opponent controls u :
 - ▶ nature
 - ▶ competitor, supplier or customer
 - ▶ market
 - ▶ Akin to a *leader-follower game*: we (leader) make a decision on x and the opponent (follower) gets to choose u after we made our decision
 - ▶ the opponent has a PhD in optimisation and will pick u that violate the user's constraints

Robust shortest path

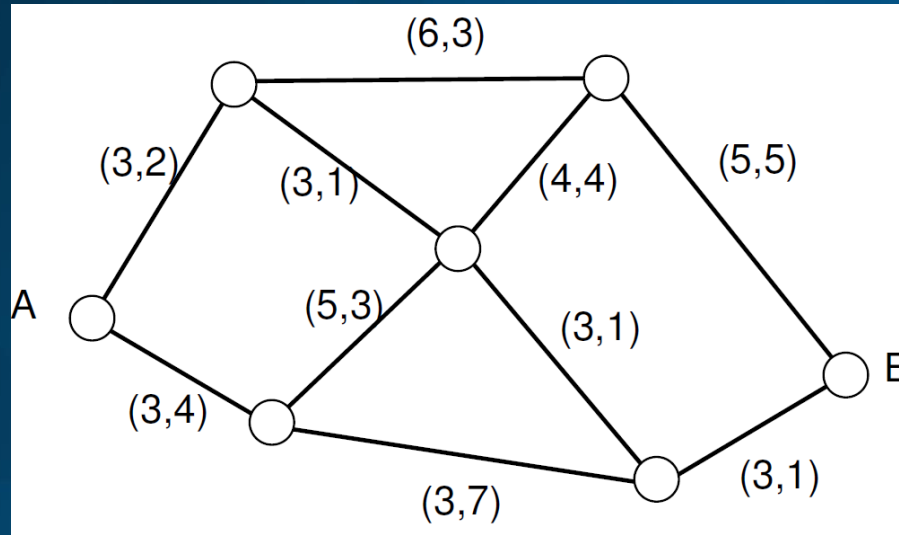
A simple example

Robust shortest path

- ▶ Find the shortest route from A to B on the city's road network
 - ▶ it takes c_e minutes to drive on road e
 - ▶ unless there's construction work, and then it's $c_e + d_e$
 - ▶ we don't know where the construction work is
 - ▶ but we know it is on at most k roads
- ▶ **Decider:** the user
- ▶ **Opponent:** city's contractors, with k crews working every day

Robust shortest path

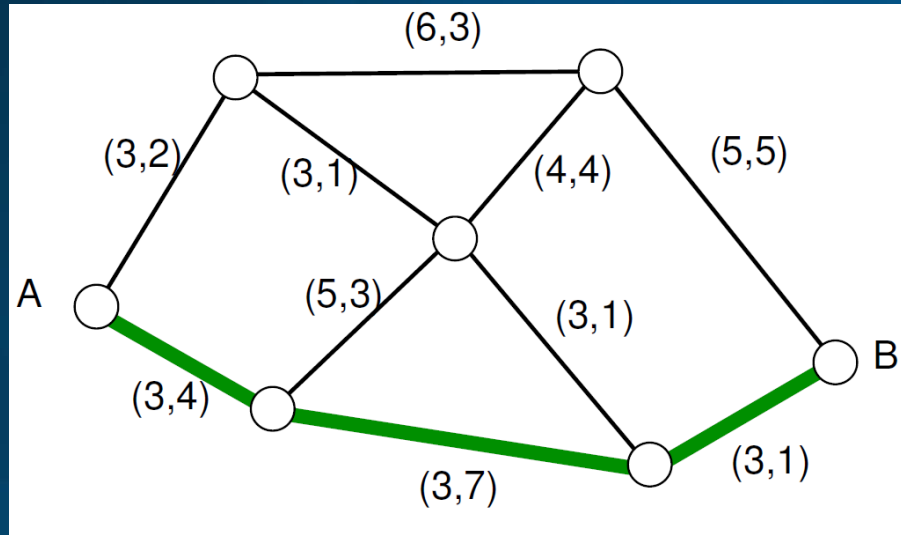
- ▶ Each link e has (c_e, d_e) . Suppose at most $k = 2$ construction zones.



- ▶ How long to get from A to B?

Robust shortest path

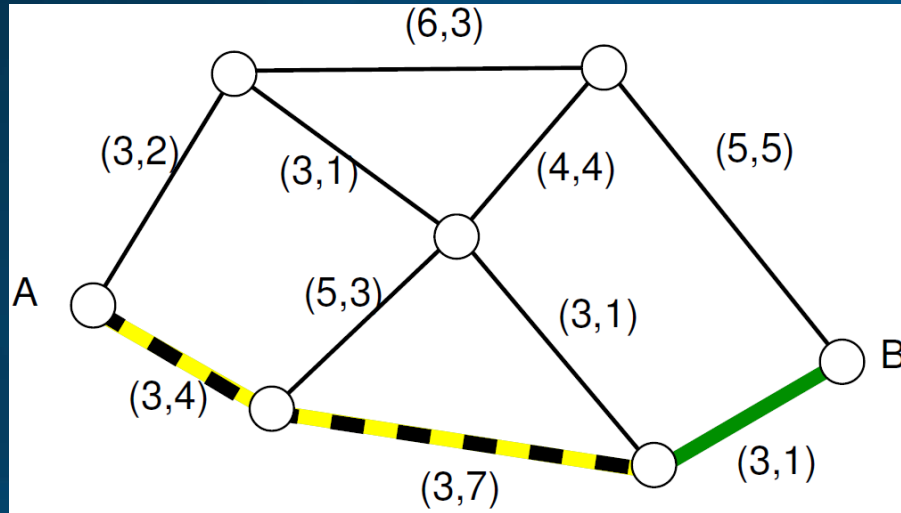
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Robust shortest path

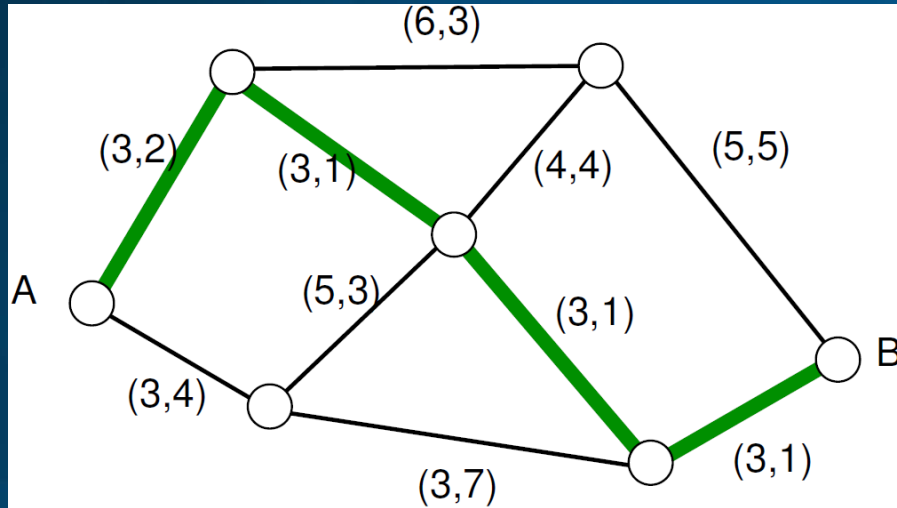
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- ▶ How long to get from A to B?

Robust shortest path

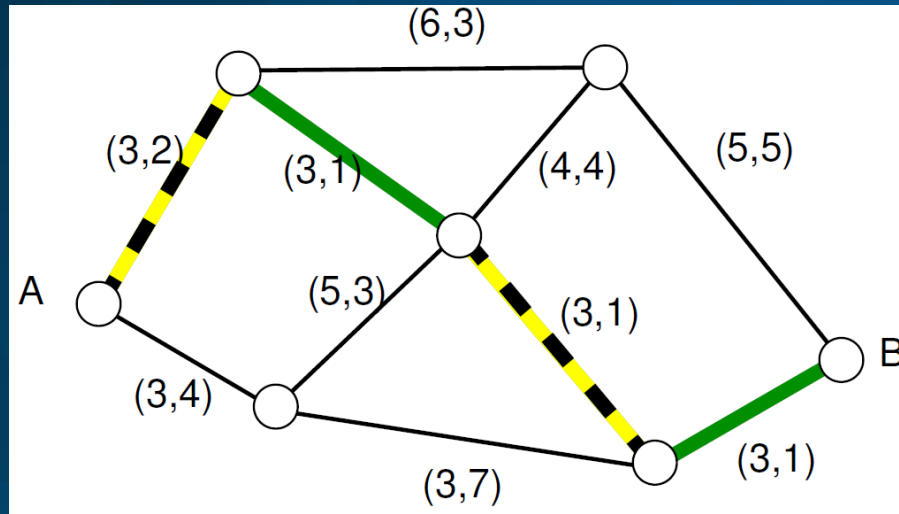
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- ▶ How long to get from A to B?

Robust shortest path

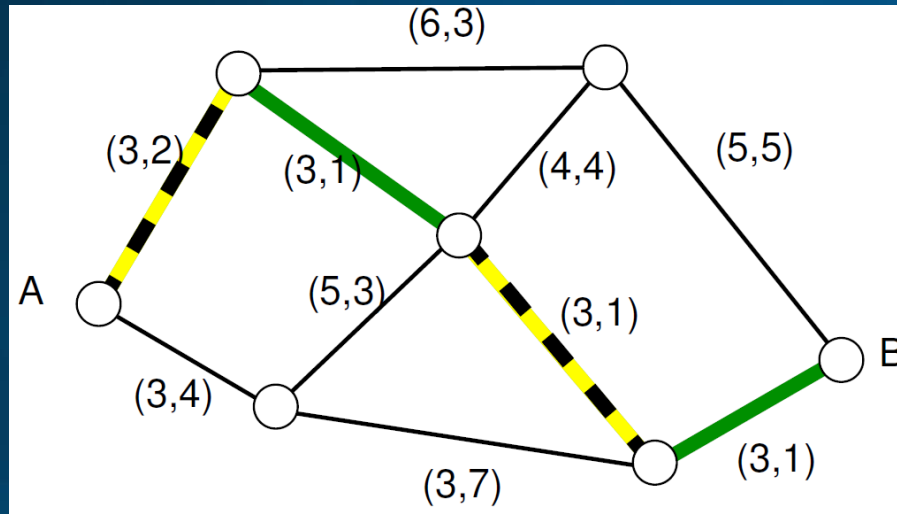
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- ▶ How long to get from A to B?

Robust shortest path

- ▶ Each link e has (c_e, d_e) . Suppose at most $k = 2$ construction zones.



- ▶ An example implementation: [roadworks.mos](https://www.fico.com/roa/roadworks/mos)

Robust knapsack

Project selection

Robust knapsack – project selection

- ▶ Select among five projects such that
 - ▶ total profit is maximised (each project has profit p_i)
 - ▶ total cost is within budget B
 - ▶ cost of each project: $c_i = a_i + u_i$, with u_i uncertain
- minimise $p_1x_1 + p_2x_2 + p_3x_3 + p_4x_4 + p_5x_5$
s.t. $c_1x_1 + c_2x_2 + c_3x_3 + c_4x_4 + c_5x_5 \leq B$
 $x_1, x_2, x_3, x_4, x_5 \in \{0,1\}$

Robust knapsack – project selection

- ▶ Suppose we know $U = \{u_i \geq 0, i = 1, 2, \dots, 5, \sum_{i=1}^5 u_i \leq 0.04\}$

- ▶ then we want to solve the following robust counterpart

$$\begin{aligned} & \text{minimise } \sum_{i=1}^5 p_i x_i \\ & \text{s.t. } \max \left\{ \sum_{i=1}^5 (a_i + u_i) x_i \right\} \leq B \\ & \quad x_1, x_2, x_3, x_4, x_5 \in \{0, 1\} \end{aligned}$$

- ▶ Alternatively, \mathbf{u} has mean 0 with covariance matrix Q and confidence level α , i.e. $\mathbf{u}^T Q \mathbf{u} \leq \alpha$

$$\begin{aligned} & \text{minimise } \sum_{i=1}^5 p_i x_i \\ & \text{s.t. } \max_{\mathbf{u}: \mathbf{u}^T Q \mathbf{u} \leq \alpha} \left\{ \sum_{i=1}^5 (a_i + u_i) x_i \right\} \leq B \\ & \quad x_1, x_2, x_3, x_4, x_5 \in \{0, 1\} \end{aligned}$$

Robust knapsack – project selection

- ▶ Another alternative: we don't have a model for u , but we have historical data: values for u for the past 12 years: u^{2013} , u^{2012} , ..., u^{2002} .
- ▶ We at least require that our constraint be satisfied for the past values of u .

$$\begin{aligned} &\text{minimise } \sum_{i=1}^5 p_i x_i \\ &\text{s.t. } \sum_{i=1}^5 (a_i + u_i^{2013}) x_i \leq B \\ &\quad \sum_{i=1}^5 (a_i + u_i^{2012}) x_i \leq B \\ &\quad \vdots \\ &\quad \sum_{i=1}^5 (a_i + u_i^{2002}) x_i \leq B \\ &\quad x_1, x_2, x_3, x_4, x_5 \in \{0,1\} \end{aligned}$$

- ▶ Some example implementations:
 - ▶ [knapsack_basic.mos](#), [knapsack_ellipsoid.mos](#), [knapsack_scenario.mos](#)

To summarise

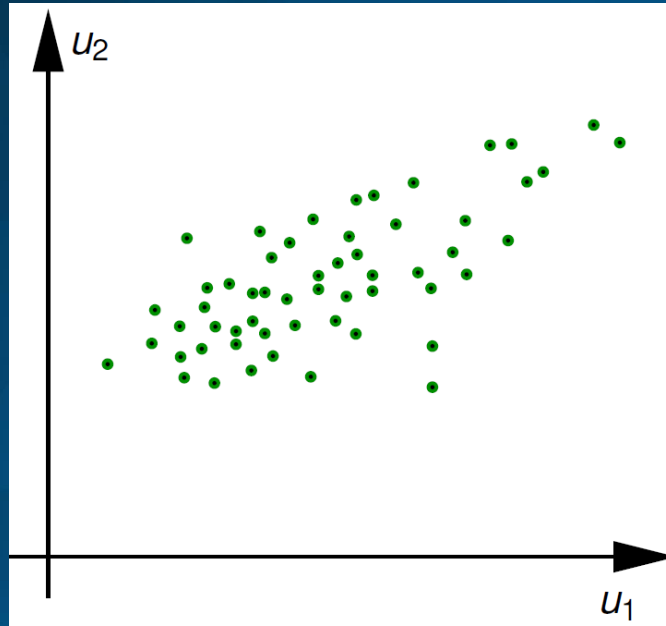
- ▶ There are several classes of uncertainty set
 - ▶ **polyhedral**: a system of linear equations/inequalities on \mathbf{u}
 - ▶ **ellipsoidal**: a quadratic constraint $\mathbf{u}^T \mathbf{Q} \mathbf{u} \leq \alpha$
 - ▶ **scenarios**: a list of historical values of \mathbf{u}
- ▶ To solve the problem
 1. construct the **robust counterpart**, a robust version of the problem
 2. solve the robust counterpart
 3. return the optimal solution of the robust counterpart as the solution of the original problem.

How does robustness change problem difficulty

- ▶ If a **polyhedral** or **scenario** uncertainty set are added, the problem remains of the same class
 - ▶ LP \rightarrow LP
 - ▶ MILP \rightarrow MILP
 - ▶ MIQCQP \rightarrow MIQCQP
- ▶ A **quadratic** uncertainty set introduces a *second order cone*:
 - ▶ LP \rightarrow Second Order Conic Programming (SOCP)
 - ▶ MILP \rightarrow MISOCP
 - ▶ MIQCQP \rightarrow MIQCQP + MISOCP

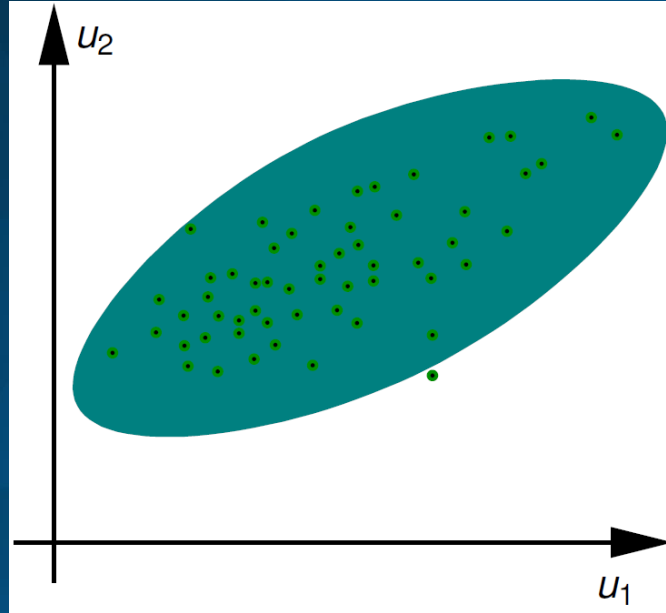
In practice ...

- ▶ Suppose we have some historical data, but not enough



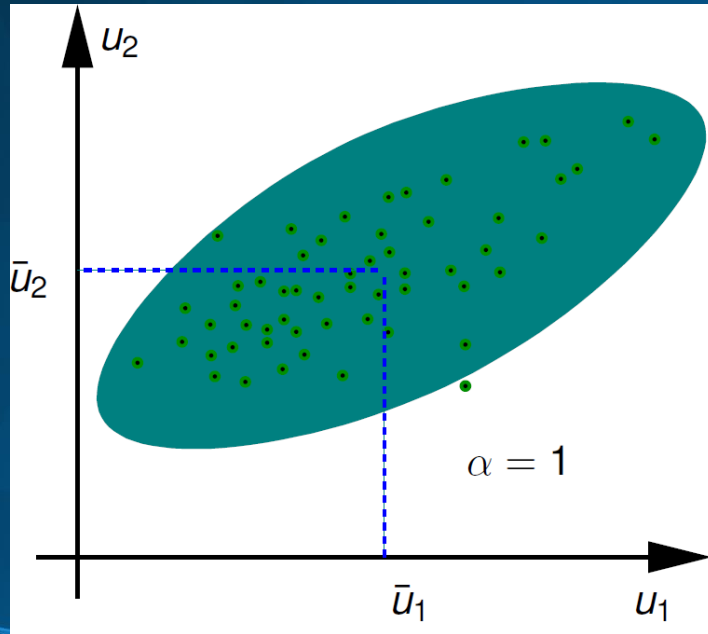
In practice ...

- ▶ Analytics can be used to yield a pattern (mean/covariance).
- ▶ Exploit it!



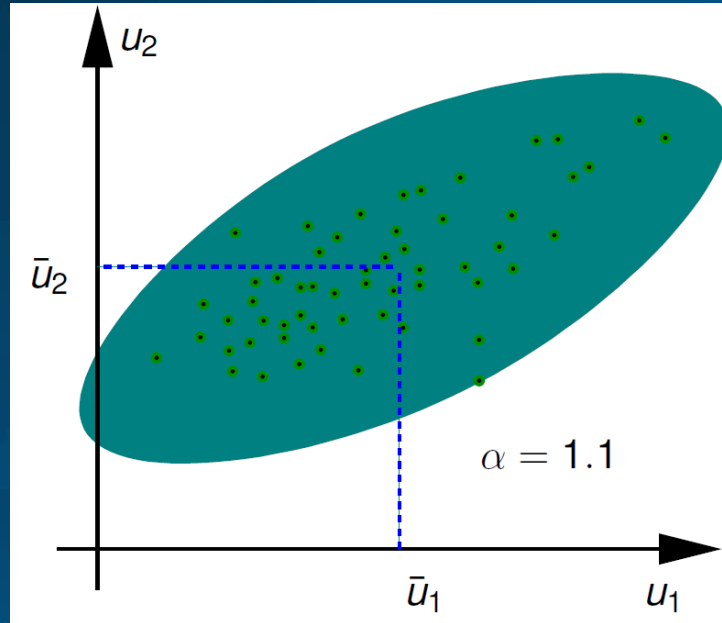
In practice ...

- ▶ Quadratic uncertainty: $\mathbf{u} = \bar{\mathbf{u}} + \tilde{\mathbf{u}}$ with $\tilde{\mathbf{u}}^T \mathbf{Q} \tilde{\mathbf{u}} \leq \alpha$



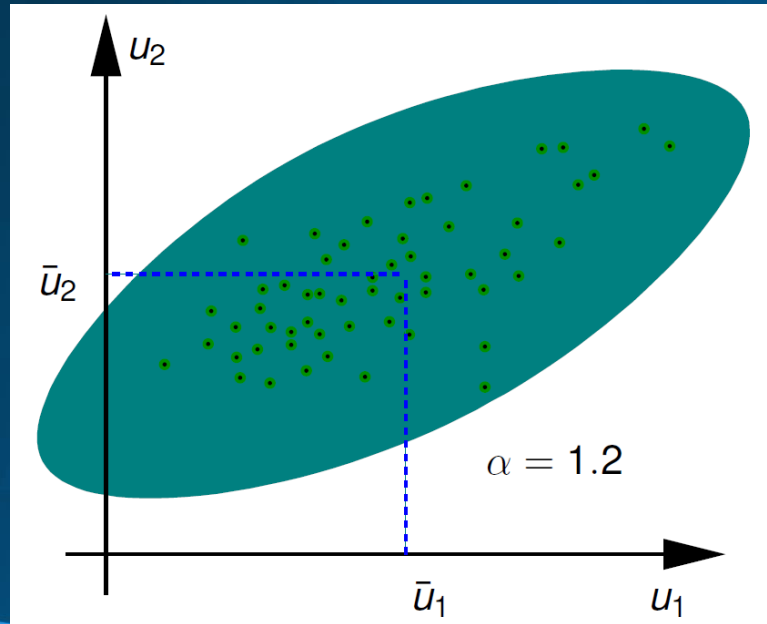
In practice ...

- ▶ Our level of uncertainty (conservativeness) is given by α



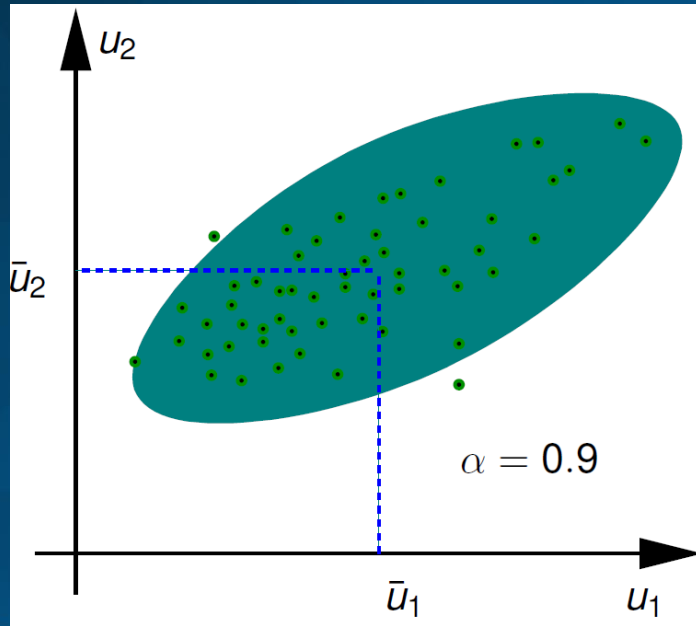
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In practice ...

- ▶ Our level of uncertainty (conservativeness) is given by α



Reference material

- ▶ White paper Robust Optimization with Xpress
 - ▶ Explains the underlying concepts and documents the Robust Optimisation examples distributed in the Xpress release
- ▶ Ben-Tal, A., El Ghaoui, L., Nemirovski, A. (2009). *Robust optimization*. Princeton University Press.
- ▶ Bertsimas, D., Sim, M. (2004). The price of robustness. *Operations Research*, **52**(1), 35-53

Thank You

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